

# Towards Combining Statistical Relational Learning and Graph Neural Networks for Reasoning

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# Relational Data/Graphs are Ubiquitous

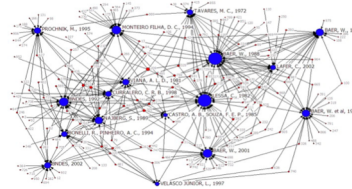
- Graphs: a general and flexible data structure to encode the relations between objects



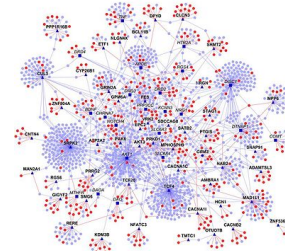
**Social Graph**



**Road Graph**

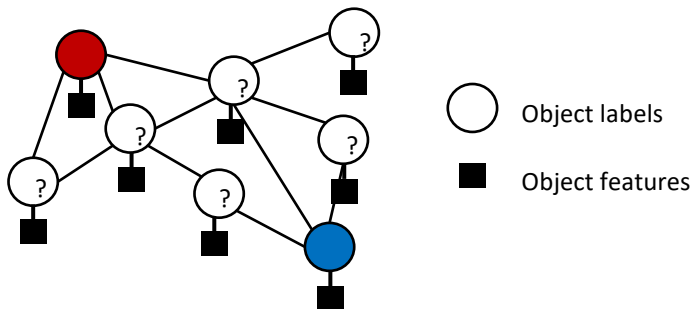


**Citation Graph**

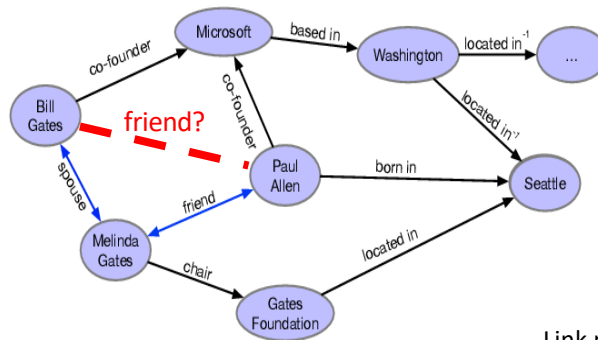


**Protein-protein  
Interaction Graph**

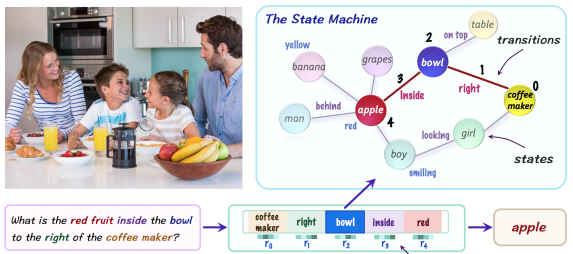
# Relational Prediction and Reasoning



Node classification

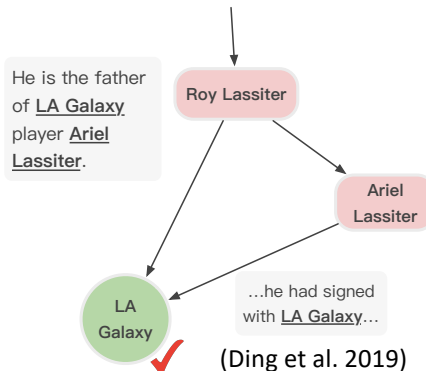


Link prediction on knowledge graphs



Visual relational reasoning  
(Hudson et al. 2019)

Q: What Cason, CA soccer team features the son of Roy Lassiter?

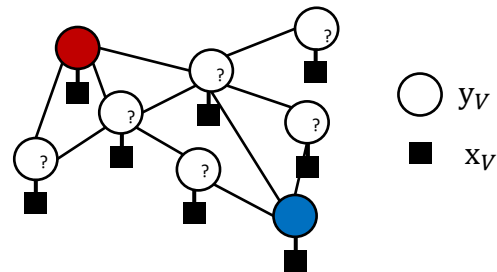


Multi-hop Question answering

(Ding et al. 2019)

# Statistical Relational Learning

- Probabilistic graphical models for relational data
  - Markov Networks (Ross et al. 1980)
  - Conditional Random Fields (Lafferty et al. 2001)
  - Markov Logic Networks (Richardson and Domingos, 2006)
- Pros:
  - Captures uncertainty and domain knowledge
  - Collective inference
- Cons:
  - Limited model capacity
  - Inference is difficult



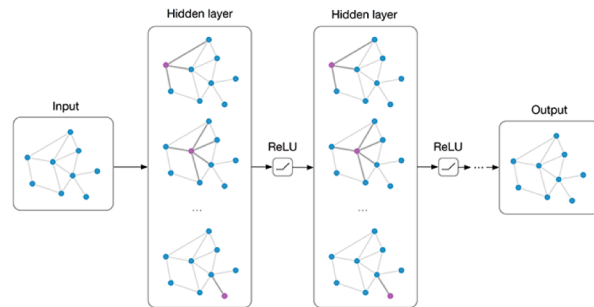
$$p(\mathbf{y}_V | \mathbf{x}_V) = \frac{1}{Z(\mathbf{x}_V)} \prod_{(i,j) \in E} \psi_{i,j}(\mathbf{y}_i, \mathbf{y}_j, \mathbf{x}_V)$$

Figure: Conditional Random Fields

# Graph Representation Learning

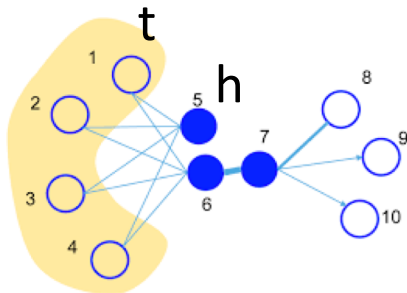
- Graph Neural Networks

- Graph convolutional Networks (Kipf et al. 2016)
- Graph attention networks (Veličković et al. 2017)
- Neural message passing (Gilmer et al. 2017)

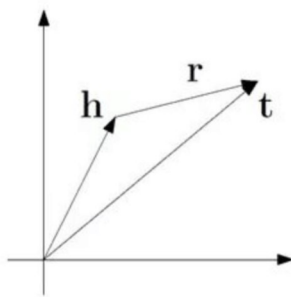


Graph convolutional Networks  
(Kipf et al. 2016)

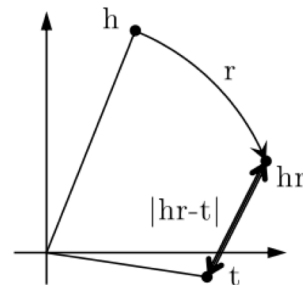
- Node Embedding and Knowledge Graph Embedding



DeepWalk, LINE, node2vec  
(Perozzi et al. 2014, Tang et al. 2015,  
Grover et al. 2016 )



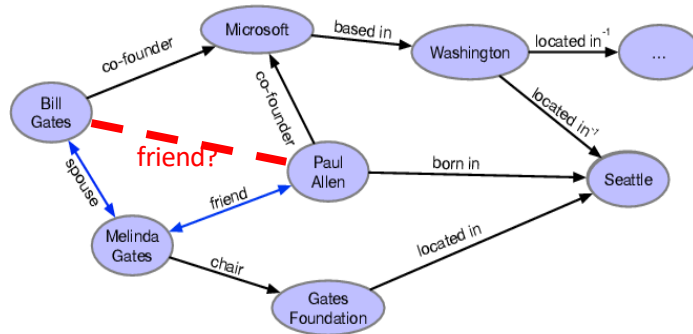
TransE  
(Bordes et al. 2013)



RotatE  
(Sun et al. 2019)

# Link Prediction on Knowledge Graphs

- A set of facts  $KG = \{(h, r, t)\}$  represented as triplets
  - (Bill\_Gates, Co\_Founder, Microsoft)
- A variety of applications
  - Question answering
  - Search
  - Recommender Systems
  - Natural language understanding
  - ...
- A fundamental problem: **predicting the missing facts by reasoning with existing facts**



# Traditional Symbolic Logic-Rule based approaches

- Expert systems: hard logic rules
  - E.g.,  $\forall X, Y, \text{Husband}(X, Y) \Rightarrow \text{Wife}(Y, X)$
  - $\forall X, Y, \text{Live}(X, Y) \Rightarrow \text{Nationality}(X, Y)$
- Problematic as logic rules can be imperfect or contradictory
- We must handle the uncertainty of logic rules

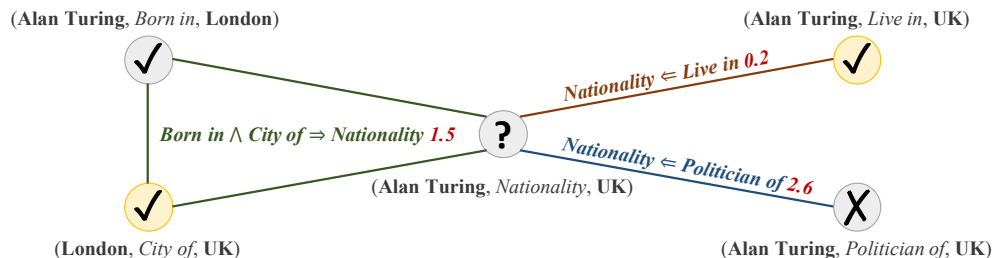
# Markov Logic Networks (Richardson and Domingos, 2006)

- Combines first-order logic and probabilistic graphical models

0.2     $\text{Live}(X, Y) \Rightarrow \text{Nationality}(X, Y)$

2.6     $\text{Politician\_of}(X, Y) \Rightarrow \text{Nationality}(X, Y)$

1.5     $\text{Born}(X, Y) \wedge \text{City\_of}(Y, Z) \Rightarrow \text{Nationality}(X, Z)$



$$p(\mathbf{v}_O, \mathbf{v}_H) = \frac{1}{Z} \exp \left( \sum_{l \in L} w_l \sum_{g \in G_l} \mathbb{1}\{g \text{ is true}\} \right) = \frac{1}{Z} \exp \left( \sum_{l \in L} w_l n_l(\mathbf{v}_O, \mathbf{v}_H) \right)$$

$V_O$ : observed facts

$V_H$ : unobserved/hidden facts

$w_l$ : weight of logic rule  $l$

$n_l(V_O, V_H)$ : number of true grounds of the logic rule  $l$



# Pros and Cons of Markov Logic Networks

- Pros

- Effectively leverage domain knowledge with logic rules
- Handle the uncertainty

- Limitation

- Inference is difficult due to complicated graph structures
- Recall is low since many facts are not covered by any logic rules

# Knowledge Graph Embeddings

- Learning the entity and relation embeddings for predicting the missing facts (e.g., TransE, ComplEx, DisMult, RotatE)
- Defining the joint distribution of all the facts

$$p(\mathbf{v}_O, \mathbf{v}_H) = \prod_{(h,r,t) \in O \cup H} \text{Ber}(\mathbf{v}_{(h,r,t)} | f(\mathbf{x}_h, \mathbf{x}_r, \mathbf{x}_t)),$$

An example:

$$\text{Ber}(\mathbf{v}_{(h,r,t)} | f(\mathbf{x}_h, \mathbf{x}_r, \mathbf{x}_t)) = \sigma(\gamma - \|\mathbf{x}_h + \mathbf{x}_r - \mathbf{x}_t\|) \quad \sigma \text{ is the sigmoid function, } \gamma \text{ is a fixed margin}$$

- Trained by treating  $V_O$  as positive facts and  $V_H$  as negative facts

# Pros and Cons

- Pros
  - Can be effectively and efficiently trained by SGD
  - High recall of missing link prediction with entity and relation embeddings
- Cons
  - Hard to leverage domain knowledge (logic rules)

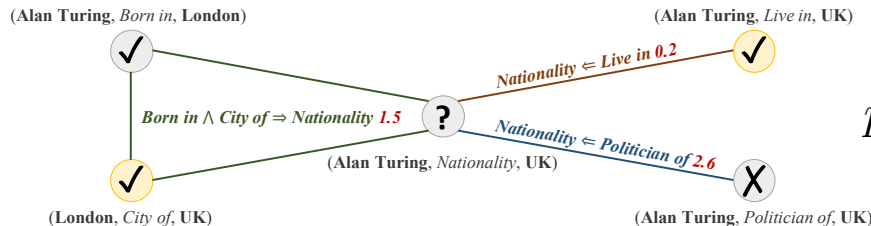
# Probabilistic Logic Neural Networks for Reasoning (Qu and Tang, NeurIPS'19. )

- Towards combining Markov Logic Networks and knowledge graph embedding
  - Leverage logic rules and handling their uncertainty
  - Effective and efficient inference
- Define the joint distribution of facts with Markov Logic Network
- Optimization with variational EM
  - Parametrize the variational distribution with knowledge graph embedding methods

Meng Qu and Jian Tang. “Probabilistic Logic Neural Networks for Reasoning.” To appear in NeurIPS'2019.

# pLogicNet

- Define the joint distribution of facts with an MLN



$$p_w(\mathbf{v}_O, \mathbf{v}_H) = \frac{1}{Z} \exp \left( \sum_l w_l n_l(\mathbf{v}_O, \mathbf{v}_H) \right)$$

- Learning by maximizing the variational lower-bound of the log-likelihood of observed facts

$$\log p_w(\mathbf{v}_O) \geq \mathcal{L}(q_\theta, p_w) = \mathbb{E}_{q_\theta(\mathbf{v}_H)} [\log p_w(\mathbf{v}_O, \mathbf{v}_H) - \log q_\theta(\mathbf{v}_H)].$$

# Inference

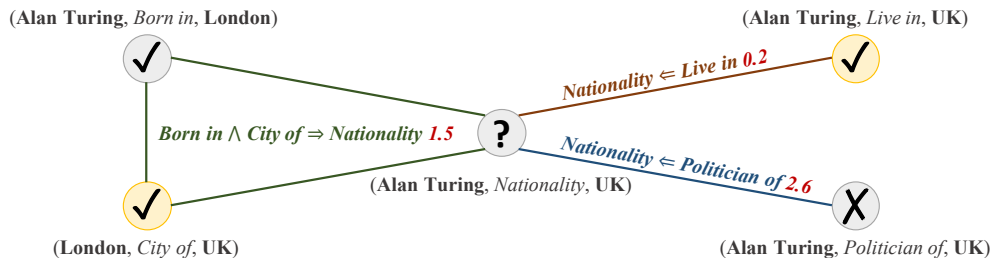
- Amortized mean-field variational inference
  - Use knowledge graph embedding model to parameterize the variational distribution

$$q_{\theta}(\mathbf{v}_H) = \prod_{(h,r,t) \in H} q_{\theta}(\mathbf{v}_{(h,r,t)}) = \prod_{(h,r,t) \in H} \text{Ber}(\mathbf{v}_{(h,r,t)} | f(\mathbf{x}_h, \mathbf{x}_r, \mathbf{x}_t)),$$

# Learning

- Optimize pseudo-likelihood function
  - Update the weights of logic rules

$$\ell_{PL}(w) \triangleq \mathbb{E}_{q_{\theta}(\mathbf{v}_H)} \left[ \sum_{h,r,t} \log p_w(\mathbf{v}_{(h,r,t)} | \mathbf{v}_{O \cup H \setminus (h,r,t)}) \right] = \mathbb{E}_{q_{\theta}(\mathbf{v}_H)} \left[ \sum_{h,r,t} \log p_w(\mathbf{v}_{(h,r,t)} | \mathbf{v}_{MB(h,r,t)}) \right].$$



# Performance of Link Prediction

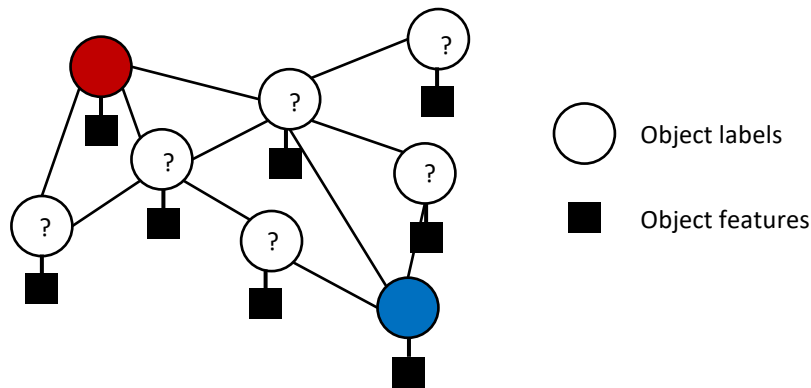
- **Datasets:** benchmark knowledge graphs
  - FB15K, WN18, FB15K-237, WN18-RR
- Logic rules:
  - Composition rules (e.g., Father of Father is GrandFather)
  - Inverse rules (e.g., Husband and Wife)
  - Symmetric rules (e.g., Similar)
  - Subrelation rules (e.g., Man => Person)

Category	Algorithm	FB15k					WN18				
		MR	MRR	H@1	H@3	H@10	MR	MRR	H@1	H@3	H@10
KGE	TransE [3]	40	0.730	64.5	79.3	86.4	272	0.772	70.1	80.8	92.0
	DistMult [17]	42	0.798	-	-	89.3	655	0.797	-	-	94.6
	HolE [26]	-	0.524	40.2	61.3	73.9	-	0.938	93.0	94.5	94.9
	ComplEx [41]	-	0.692	59.9	75.9	84.0	-	0.941	93.6	94.5	94.7
	ConvE [8]	51	0.657	55.8	72.3	83.1	374	0.943	93.5	94.6	95.6
Rule-based	BLP [7]	415	0.242	15.1	26.9	42.4	736	0.643	53.7	71.7	83.0
	MLN [32]	352	0.321	21.0	37.0	55.0	717	0.657	55.4	73.1	83.9
Hybrid	RUGE [15]	-	0.768	70.3	81.5	86.5	-	-	-	-	-
	NNE-AER [9]	-	0.803	76.1	83.1	87.4	-	0.943	<b>94.0</b>	94.5	94.8
Ours	pLogicNet	<b>33</b>	0.792	71.4	85.7	90.1	255	0.832	71.6	94.4	95.7
	pLogicNet*	<b>33</b>	<b>0.844</b>	<b>81.2</b>	<b>86.2</b>	<b>90.2</b>	<b>254</b>	<b>0.945</b>	93.9	<b>94.7</b>	<b>95.8</b>



# Semi-supervised Object Classification

- Given  $G = (V, E, \mathbf{x}_V)$ 
  - $V = V_L \cup V_U$ : objects/nodes
  - $E$ : edges
  - $\mathbf{x}_V$ : object features



- Give some labeled objects  $V_L$ , we want to infer the labels of the rest of objects  $V_U$

# GMNN: Graph Markov Neural Networks (Qu, Bengio, and Tang, ICML'19)

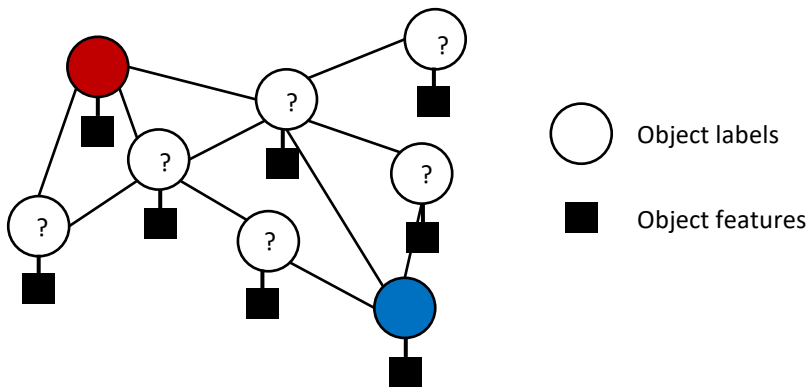
- Combining conditional random fields and graph neural networks
  - Learning effective node representations
  - Modeling the label dependencies of nodes
- Model the joint distribution of object labels  $\mathbf{y}_V$  conditioned on object attributes  $\mathbf{x}_V$ , i.e.,  $p_\phi(\mathbf{y}_V|\mathbf{x}_V)$  with CRFs
  - Optimization with Pseudolikelihood Variational-EM

$$\log p_\phi(\mathbf{y}_L|\mathbf{x}_V) \geq$$

$$\mathbb{E}_{q_\theta(\mathbf{y}_U|\mathbf{x}_V)} [\log p_\phi(\mathbf{y}_L, \mathbf{y}_U|\mathbf{x}_V) - \log q_\theta(\mathbf{y}_U|\mathbf{x}_V)]$$

# Overall Optimization Procedure

- Two Graph Neural Networks Collaborate with each other
  - $p_\phi$ : learning network, modeling the label dependency
  - $q_\theta$ : inference network, learning the object representations
- $q_\theta$  infer the labels of unlabeled objects trained with supervision from  $p_\phi$  and labeled objects
- $p_\phi$  is trained with a fully labeled graph, where the unlabeled objects are labeled by  $q_\theta$



# Take Away

- Relational reasoning is important to a variety of applications
  - Node classification, link prediction on knowledge graphs, question answering
- Towards combining two learning frameworks
  - Statistical Relational Learning
  - Graph Representation Learning
- Looking forward
  - Combining deep learning and symbolic reasoning systems
  - Incorporating common sense knowledge, handling uncertainty, and maybe automatically learn the logic rules.

Questions?  
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# Results on FB15k-237 and WN18RR

Category	Algorithm	FB15k-237					WN18RR				
		MR	MRR	H@1	H@3	H@10	MR	MRR	H@1	H@3	H@10
<b>KGE</b>	TransE [3]	181	0.326	22.9	36.3	52.1	3410	0.223	1.3	40.1	53.1
	DistMult [17]	254	0.241	15.5	26.3	41.9	5110	0.43	39	44	49
	ComplEx [41]	339	0.247	15.8	27.5	42.8	5261	<b>0.44</b>	<b>41</b>	<b>46</b>	51
	ConvE [8]	244	0.325	<b>23.7</b>	35.6	50.1	4187	0.43	40	44	52
<b>Rule-based</b>	BLP [7]	1985	0.092	6.2	9.8	15.0	12051	0.254	18.7	31.3	35.8
	MLN [32]	1980	0.098	6.7	10.3	16.0	11549	0.259	19.1	32.2	36.1
<b>Ours</b>	pLogicNet	<b>173</b>	0.330	23.1	<b>36.9</b>	<b>52.8</b>	3436	0.230	1.5	41.1	53.1
	pLogicNet*	<b>173</b>	<b>0.332</b>	<b>23.7</b>	36.7	52.4	<b>3408</b>	<b>0.441</b>	39.8	44.6	<b>53.7</b>

# GMNN: Graph Markov Neural Networks

- Model the joint distribution of object labels  $\mathbf{y}_V$  conditioned on object attributes  $\mathbf{x}_V$ , i.e.,  $p_\phi(\mathbf{y}_V|\mathbf{x}_V)$
- Learning the model parameters  $\phi$  by maximizing the lower-bound of log-likelihood of the observed data,  $\log p_\phi(\mathbf{y}_L|\mathbf{x}_V)$

$$\log p_\phi(\mathbf{y}_L|\mathbf{x}_V) \geq \mathbb{E}_{q_\theta(\mathbf{y}_U|\mathbf{x}_V)} [\log p_\phi(\mathbf{y}_L, \mathbf{y}_U|\mathbf{x}_V) - \log q_\theta(\mathbf{y}_U|\mathbf{x}_V)]$$

# Optimization with Pseudolikelihood Variational-EM

- E-step: fix  $p_\phi$  and update the variational distribution  $q_\theta(\mathbf{y}_U|\mathbf{x}_V)$  to approximate the true posterior distribution  $p_\phi(\mathbf{y}_U|\mathbf{y}_L, \mathbf{x}_V)$ .
- M-step: fix  $q_\theta$  and update  $p_\phi$  to maximize the lower bound

$$\ell(\phi) = \mathbb{E}_{q_\theta(\mathbf{y}_U|\mathbf{x}_V)}[\log p_\phi(\mathbf{y}_L, \mathbf{y}_U|\mathbf{x}_V)]$$

- Directly optimize the joint likelihood is difficult due to the partition function in  $p_\phi$ , instead we optimize the pseudolikelihood function

$$\begin{aligned}\ell_{PL}(\phi) &\triangleq \mathbb{E}_{q_\theta(\mathbf{y}_U|\mathbf{x}_V)}\left[\sum_{n \in V} \log p_\phi(\mathbf{y}_n|\mathbf{y}_{V \setminus n}, \mathbf{x}_V)\right] \\ &= \mathbb{E}_{q_\theta(\mathbf{y}_U|\mathbf{x}_V)}\left[\sum_{n \in V} \log p_\phi(\mathbf{y}_n|\mathbf{y}_{\text{NB}(n)}, \mathbf{x}_V)\right]\end{aligned}$$



# Inference/E-step: approximate $p_\phi(\mathbf{y}_U | \mathbf{y}_L, \mathbf{x}_V)$

- Approximate it with variational distribution  $q_\theta(\mathbf{y}_U | \mathbf{x}_V)$ . Specifically we use mean-field method:

$$q_\theta(\mathbf{y}_U | \mathbf{x}_V) = \prod_{n \in U} q_\theta(\mathbf{y}_n | \mathbf{x}_V).$$

- We parametrize each variational distribution with a Graph Neural Network

$$q_\theta(\mathbf{y}_n | \mathbf{x}_V) = \text{Cat}(\mathbf{y}_n | \text{softmax}(W_\theta \mathbf{h}_{\theta,n}))$$

Object representations learned by GNN



# Learning/M-step:

- The log-pseudo likelihood:

$$\begin{aligned}\ell_{PL}(\phi) &\triangleq \mathbb{E}_{q_{\theta}(\mathbf{y}_U|\mathbf{x}_V)}\left[\sum_{n \in V} \log p_{\phi}(\mathbf{y}_n|\mathbf{y}_{V \setminus n}, \mathbf{x}_V)\right] \\ &= \mathbb{E}_{q_{\theta}(\mathbf{y}_U|\mathbf{x}_V)}\left[\sum_{n \in V} \log p_{\phi}(\mathbf{y}_n|\mathbf{y}_{NB(n)}, \mathbf{x}_V)\right]\end{aligned}$$

- According to the inference, only the  $p_{\phi}(\mathbf{y}_n|\mathbf{y}_{NB(n)}, \mathbf{x}_V)$  is required
- Parametrize  $p_{\phi}(\mathbf{y}_n|\mathbf{y}_{NB(n)}, \mathbf{x}_V)$  with another GCN

$$p_{\phi}(\mathbf{y}_n|\mathbf{y}_{NB(n)}, \mathbf{x}_V) = \text{Cat}(\mathbf{y}_n|\text{softmax}(W_{\phi}\mathbf{h}_{\phi,n}))$$

# Overall Optimization Procedure

- Two Graph Neural Networks Collaborate with each other
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  - $q_\theta$ : inference network, learning the object representations
- $q_\theta$  infer the labels of unlabeled objects trained with supervision from  $p_\phi$  and labeled objects
- $p_\phi$  is trained with a fully labeled graph, where the unlabeled objects are labeled by  $q_\theta$

